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MANAGEMENT OF PARAMETERIZED DESIGN ASSEMBLY CODING SYSTEMS

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Abstract: In the machine building industry, the classification and coding of parts, subassemblies and assemblies have a special importance. The relationship between classifications and codifications is defined by the degree of their interdependence or overlap. The main objective of coding, which also determines its basic function, is identification. If it also takes on the meanings of the relations between the elements of the set, it also fulfills the function of representing the classification. In this paper we want to present an innovative coding system for assemblies in the design phase, more precisely the parameterized design.

Keywords: parameterized modeling, configuration, classification and coding, variable parameters

1. INTRODUCTION

Manufacturing design is a multilateral approach to the production of goods and it integrates constructive design processes with materials, processes/manufacturing methods, design of technological processes, assembly, testing, quality assurance and maintenance [6].

Simultaneous engineering (also called parallel or convergent) can be defined as a systematic approach to integrating the simultaneous design of products and processes related to this, including manufacturing, preparatory activities, maintenance and many other product life cycle considerations such as the required series of tests, verifications, reliability, safety, human factors and material recycling. The purpose of simultaneous engineering is to design and manufacture a product in pursuit such a way that the product meets the customer's requirements to the greatest extent.

Basically, these codes consist of a series of fields that encode the type parts/surfaces, materials, overall dimensions, accuracy, certain aspects with technological character.

2. DESCRIPTION OF THE OPERATING PRINCIPLE FOR PARAMETER CODING SYSTEM

It is considered the linear hydraulic motor in the figure, from which the rod/piston will be extracted together with the hydraulic seals mounted on the piston body, in order to exemplify the method of coding for the parameters associated with the 3D model [1-4, 8].

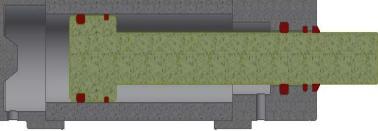


Figure 1 ~ The linear hydraulic motor

To perform the calculations necessary to determine the values of the parameters necessary for the 3D model, a configurator file designed in excel is used. To filter the parameters, in the sense of allocating them only to the components that use them directly, an ipt file is used in which all the parameters from the excel file are imported.



	А	В	С	D	E	Area of use	_	Parameter code structure									
1	Parameter	Value	u.m.	Description	Group	Description	Code			rea of							
2	Z2 F2 D 001	30	mm	Piston rod diameter		Input data	1			1 0 A 0 1							
3	Z4_F2_L_001	280	mm	Rod length	1 1	Sketching environment	2			Functional character							
4	Z2 F2 D 002		mm	Piston body diameter	1 1	Features of the 3D model	3							+ D	escribed	geometr	у
4						Part modeling environment	4	╎┌┴	-			- r	4			_	
5	Z4_F2_L_002		mm	Piston body length		Assembly environment	5	Z		-	F	-		· -			
6	Z2_F3_L_001	7	mm	Channel 1 positioning	<u> </u>	2D drawing environment	6		-			۰ ۲	_		<u> </u>		
7	Z2_F2_L_003	10	mm	Channel 1 width	+	Calculation report	7]	- 1		_	J			*		
8	Z2 F2 L 004	5	mm	Channel 1 depth	Piston	Functionality			- 1					Orde	er numbe	ir i	
9	Z2 F2 R 001	2	mm	Channel 1 radius	i E	Description	Code				L,	Functi	ional	haract	ter code		
	Z2 F3 L 002	20	mm	Distance between channels	1 1	Acționare	1				rea of		a da				
					1	Dimensională	2			• /	erea or	use o	ode				
	Z2_F2_L_005		mm	Channel width 2		Pozițională	3]				E	mple				
12	Z2_F2_L_006	3	mm	Channel 2 depth		Descriptivă	4	76.62		01					in the	asse	mbly
13	Z2_F2_R_002	1	mm	Channel 2 radius		Mărimi tehice	5									aracte	
14	Z2_F2_D_003	52	mm	Inner diameter		Described geometry		by the								der nur	
15	Z2_F2_D_004	72	mm	Outer diameter	Cylinder	Description	Code	001									
16	Z2_F2_L_002	200	mm	Cylinder length	1	No geometry	F									2D dra	
17	Z2 F2 L 007	7	mm	Sealing element	Sealing	Linear dimensions Diameter	D									cator)	
18	Z2 F2 D 005	52	mm	Sealing element	element	Radius	R	text)						geor	netry	probat	nya
	Z2 F2 L 008		mm	Sealing element	piston	Angles	U			00110							
					<u> </u>		-	11						1			
- F1	zure 2 ~	Defai	ilt par	rameters from the	e excel	Figure 3	i ~ (0011	ng	sy	ste	em	us	sed			

fault parameters from the excel configuration file

Figure 3 ~ Coding system used

The parameters imported from the excel file into the ipt file are shown in the image below which is the parameter management register within Autodesk Inventor from the ipt file used as a database for configured parameters.

Selection of the necessary parameters for the 3D model of the rod / piston.

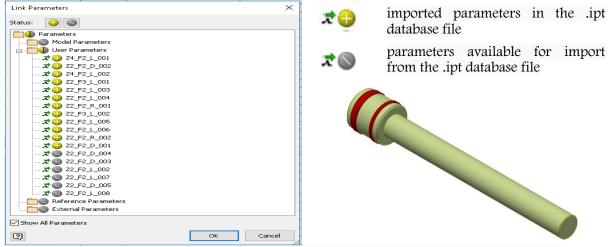
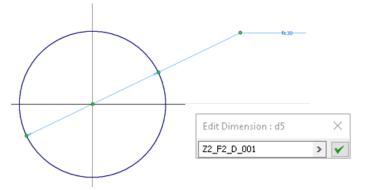


Figure 4 - Selection of the necessary parameters for the 3D model of the rod / piston The speed for updating the 3D model is higher if there are fewer parameters imported in the elements that make up the model (parts and subassemblies).

If the excel file had been linked directly as a database, it would not have been possible to select only the necessary parameters, each time a parameter was needed, inevitably the whole list of parameters generated by the file will be imported [5, 7].



Step 1 - Create a sketch that characterizes the shape and size of the rod

- Z2 we are in the environment of 2D sketches;
- F2 the parameter describes a dimension;
- the parameter represents a diameter; D
- 001 it is the first parameter defined in the final assembly which holds the code prefix Z2 F2 D;

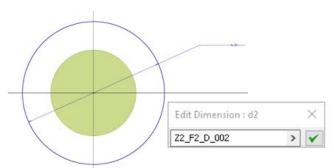




Extrude : Extrusion1		×
Shape More		
Profile	≞	Extents Distance ~
Solids	≞	Z4_F2_L_001 >
Output	₽	× × × ×
	6°	Match shape

Step 2 - Extrude the sketched geometry

- Z4 we are in the modeling environment of 3D parts;
- F2 the parameter describes a dimension;
- L the parameter represents a length;
- 001 it is the first parameter defined in the final assembly which holds the code prefix Z4_F2_L



Step 3 ~ ~ Create a sketch that characterizes the shape and size of the piston body

- Z2 we are in the environment of 2D sketches;
- F2 the parameter describes a dimension;
- D the parameter represents a diameter;
- 002 it is the second parameter defined in the final assembly which holds the code prefix Z2_F2_D

Extrude : Extrusio	in2	
Shape More		
Profile Solids	Extents Distance Z4_F2_L_002	~
Output	And and a second	XX

Step 4 ~ Extrude the sketched geometry

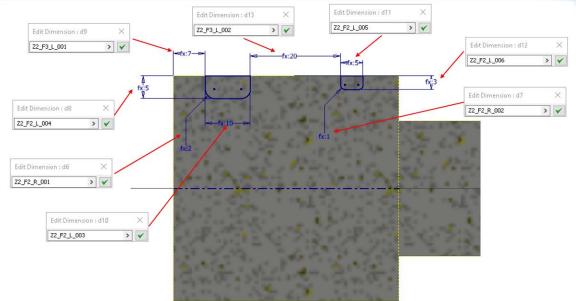
- Z4 we are in the modeling environment of 3D parts;
- F2 the parameter describes a dimension;
- L the parameter represents a length;

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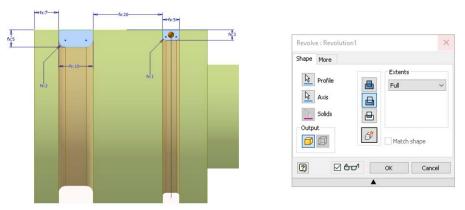
002 it is the second parameter defined in the final assembly which holds the code prefix Z4_F2_D



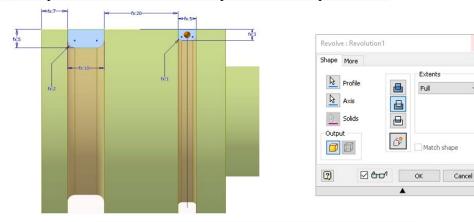


Step 5 ~ Sketch the geometry of the channels in the piston body

-	
Z2_F2_L_003	describes a dimension - representing a length - with order number 003;
Z2_F2_R_001	describes a dimension - representing a length - with order number 001;
Z2_F2_L_004	describes a dimension - representing a length - with order number 004;
Z2_F3_L_001	describes a dimension ~ representing a length ~ with order number 004;
Z2_F3_L_002	describes a dimension - representing a length - with order number 002;
Z2_F2_L_005	describes a dimension ~ representing a length ~ with order number 005;
Z2_F2_L_006	describes a dimension ~ representing a length ~ with order number 006;
Z2_F2_R_002	describes a dimension - representing a diameter - with order number 002;



Step 6 - Extrude the previous geometry around the revolution axis of the part in order to obtain the channels This operation is performed without the help of a variable parameter.



Step 7 - Perform the side chamfers of the piston edges



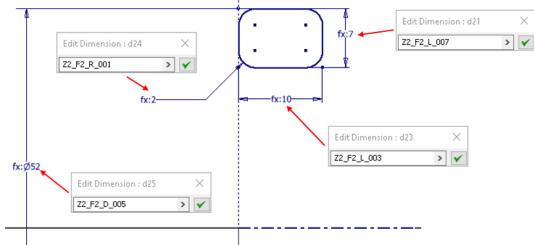
×



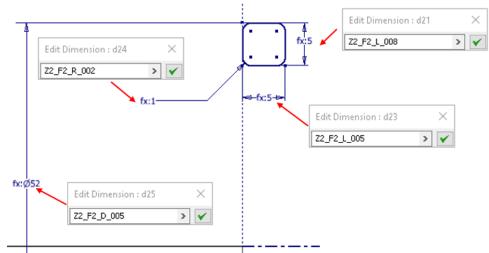
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This operation is performed without the help of a variable parameter, having a fixed parameter of 2 mm.



Step 8 - Construction of the sketch that represents the section of the first sealing elementZ2_F2_L_003describes a dimension - representing a length - with order number 003Z2_F2_R_001describes a dimension - representing a radius - with order number 001Z2_F2_L_007describes a dimension - representing a length - with order number 007Z2_F2_D_005describes a dimension - representing a diameter - with order number 005



Step 9 - Construction of the sketch that represents the section of the second sealing element
Z2_F2_L_005
Z2_F2_R_002
Z2_F2_D_005
Z2_F2_L_008
describes a dimension - representing a length - with order number 002
describes a dimension - representing a diameter - with order number 005
Z2_F2_L_008
describes a dimension - representing a length - with order number 005
rameters marked in red are also used in the cases presented above having the character of

The parameters marked in red are also used in the cases presented above, having the character of common parameters.

Parameters								X
Parameter Name	Unit/Type	Equation	Nominal Value	Tol.	Model Value	Кеу	Export	Comment
Hodel Parameters	1							
- d21	mm	Z2_F2_L_008	5,000000	0	5,000000			
- d23	mm	Z2_F2_L_005	5,000000	0	5,000000			
- d24	mm	Z2_F2_R_002	1,000000	0	1,000000			
	mm	Z2_F2_D_005	52,000000	0	52,000000			
User Parameters								
- Z2_F2_L_005	mm	5,000 mm	5,000000	0	5,000000			Latime canal 2
- Z2_F2_R_002	mm	1,000 mm	1,000000	0	1,000000			Raza canal 2
- Z2_F2_D_005	mm	52,000 mm	52,000000	0	52,000000			Garnitura
	mm	5,000 mm	5,000000	0	5,000000			Garnitura
Image: Second Secon								<< Less Done

Figure x. The common parameters



3. CONCLUSIONS

- variable parameters are always processed in the source files (in our case the excel configuration file) before being exported to the 3D model or to the filter file (example of the .ipt file);
- the 3D model can be driven through a set of a predetermined parameters with fixed value but especially by variable parameters belonging to a specific coding system;
- the code structure is based on a root used as a prefix, which has the role of describing the area of use within the 3D model of the parameter, its functionality and the type of geometry described where applicable. The code suffix is based on the serial number of the described root, being the number resulting from the chronological registration of the root of the parameter within the final set;
- parameters can be common or dedicated to a particular element or for a portion of that element;
- the large number of variable parameters increases the update time of the 3D model governed by them. An optimization solution being the selection for importing only the parameters strictly necessary for modeling certain geometries and using such a parameter in as many areas as possible;
- in the case of parts that are mutually assembled, in most cases there are common variable parameters in the contact areas through which the assembly is performed.

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